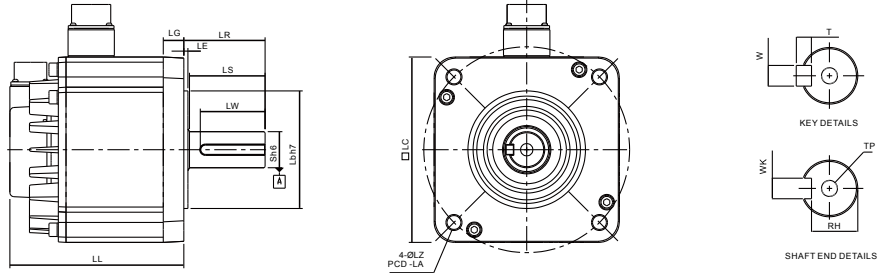


400V Series

Frame Size 180mm and above



Units: mm

Model	K Δ 1820 \square S	L Δ 1830 \square S	L Δ 1845 \square S	L Δ 1855 \square 3	L Δ 1875 \square S	M Δ 1309 \square S
LC	180	180	180	180	180	130
LZ	13.5	13.5	13.5	13.5	13.5	9
LA	200	200	200	200	200	145
S	35 ($^{+0}_{-0.016}$)	35 ($^{+0}_{-0.016}$)	35 ($^{+0}_{-0.016}$)	42 ($^{+0}_{-0.016}$)	42 ($^{+0}_{-0.016}$)	22 ($^{+0}_{-0.013}$)
LB	114.3 ($^{+0}_{-0.035}$)	114.3 ($^{+0}_{-0.035}$)	114.3 ($^{+0}_{-0.035}$)	114.3 ($^{+0}_{-0.035}$)	114.3 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)
LL (without brake)	169	202.1	235.3	279.7	342.0	163.5
LL (with brake)	203.1	235.3	279.3	311.7	376.1	198
LS	73	73	73	108.5	108.5	47
LR	79	79	79	113	113	55
LE	4	4	4	4	4	6
LG	20	20	20	20	20	11.5
LW	63	63	63	90	90	36
RH	30	30	30	37	37	18
WK	10	10	10	12	12	8
W	10	10	10	12	12	8
T	8	8	8	8	8	7
TP	M12 Depth 25	M12 Depth 25	M12 Depth 25	M16 Depth 32	M16 Depth 32	M6 Depth 20

- NOTE**
- 1) Dimensions are in millimeters.
 - 2) Dimensions of the servo motors may be revised without prior notice.
 - 3) The boxes (\square) in the model names are for optional configurations (keyway, brake and oil seal).
 - 4) The boxes (Δ) in the model names are for encoder resolution types (Δ =1: Incremental encoder, 20-bit; Δ =2: Incremental encoder, 17-bit); Δ =A: Absolute type

Speed-Torque Curves (T-N Curves)

