Autonics

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- A symbol indicates caution due to special circumstances in which hazards may occur.
- Marning Failure to follow instructions may result in serious injury or death
- Analog Non-Indication Type PID Temperature Controllers



TA Series

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Features

- Auto-tuning PID temperature control
- PID and ON/OFF control : toggle via external switch
- Deviation indicators (green, red LED)
- Control output indicator (red LED)
- Stop control output function using analog dial
- Sensor disconnect display function
- Built-in microprocessor

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
- Failure to follow this instruction may result in personal injury, economic loss or fire.
 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
- Failure to follow this instruction may result in explosion or fire. **03. Install on a device panel to use.**
- Failure to follow this instruction may result in electric shock.

Safety Considerations

- **04.** Do not connect, repair, or inspect the unit while connected to a power source. Failure to follow this instruction may result in fire or electric shock.
- **05. Check 'Connections' before wiring.** Failure to follow this instruction may result in fire.
- **06.** Do not disassemble or modify the unit. Failure to follow this instruction may result in fire or electric shock.

▲ Caution Failure to follow instructions may result in injury or product damage

- 01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m. When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.
- Failure to follow this instruction may result in fire or malfunction due to contact failure. **02. Use the unit within the rated specifications.**
- Failure to follow this instruction may result in fire or product damage **03. Use a dry cloth to clean the unit, and do not use water or organic solvent.** Failure to follow this instruction may result in fire or electric check
- Failure to follow this instruction may result in fire or electric shock.64. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
 Check the polarity of the terminals before wiring the temperature sensor. For RTD
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case installing
 power line and input signal line closely, use line filter or varistor at power line and shielded
 wire at input signal line. Do not use near the equipment which generates strong magnetic
 force or high frequency noise.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
 Make a required space around the unit for radiation of heat. For accurate temperature
- measurement, warm up the unit over 20 min after turning on the power.Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
 Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website .

| т | Α | 0 | - | В | 4 | 2 | ß | 4 | 6 | | | |
|---|------------|-------|---|---|---|----------------------------|---------------------------------------|-----------------------|---------|-------|-------|--|
| Size S: DIN W 48 × H 48 mm (8 pin plug type) M: DIN W 72 × H 72 mm L: DIN W 96 × H 96 mm | | | | Input sensor κ: K(CA) j: J(IC) P: DP100 Ω Temperature range for each sensor | | | | | | | | |
| 🖸 Con | trol o | utput | | | | Refer | to 'Inpu | t Type | and Usi | ng Ra | nge'. | |
| R: Rela S: SSR | y drive | | | | | G Ter C: Cels F: Fah | nperat sius (°C) renheit | ure un (°F) | it | | | |

Input Type and Using Range

| PN | Input type | | Using range (°C) | Using range (°F) | | |
|----|--------------|---------|------------------|------------------|--|--|
| 1 | | | 0~100 | 32 ~ 212 | | |
| 2 | | K(CA) | 0 ~ 200 | 32 ~ 392 | | |
| 4 | 1 | | 0 ~ 400 | 32 ~ 752 | | |
| 6 | Thormonounlo | | 0 ~ 600 | 32 ~ 1,112 | | |
| 8 | Inermocoupie | | 0~800 | 32 ~ 1,472 | | |
| С | | | 0 ~ 1,200 | 32 ~ 2,192 | | |
| 2 | | J(IC) | 0 ~ 200 | 32 ~ 392 | | |
| 3 |] | | 0 ~ 300 | 32 ~ 572 | | |
| 4 | | | 0 ~ 400 | 32 ~ 752 | | |
| 0 | | | -50 ~ 100 | -58 ~ 212 | | |
| 1 | | DPt100Ω | 0~100 | 32 ~ 212 | | |
| 2 | RID | | 0 ~ 200 | 32 ~ 392 | | |
| 4 |] | | 0 ~ 400 | 32 ~ 752 | | |

Product Components

• Product Bracket

• Instruction manual

Sold Separately

• 8 pin socket: PG-08, PS-08(N)

Terminal protection cover: RMA / RLA Cover

Specifications

| Series | | TA Series | | | | | |
|---------------------------|--------------|--|--|--|--|--|--|
| Power supply | | 100 - 240 VAC ~ 50/60 Hz ±10% | | | | | |
| Power co | nsumption | \leq 4 VA | | | | | |
| Sampling | g period | 100 ms | | | | | |
| Input specification | | RTD: DPt100Ω (allowable line resistance per a wire: ≤5 Ω) Thermocouple: K (CA), J (IC) | | | | | |
| Control | Relay | 250 VAC~ 3 A, 30 VDC== 1 A 1c | | | | | |
| output | SSR | $12 \text{ VDC} = \pm 2 \text{ V}, \le 20 \text{ mA}$ | | | | | |
| Display ty | уре | PV deviation, Error display (red, green), LED type | | | | | |
| Setting m | nethod | Front dial | | | | | |
| Setting accuracy | | • At room temperature (23 °C ±5 °C) Over 100 °C model: F.S.±2%, below 100 °C model: F.S.±3% • Out of room temperature range Over 100 °C model: F.S.±3%, below 100 °C model: F.S.±4% | | | | | |
| Control | ON/OFF | Hysteresis: 2°C (fixed) | | | | | |
| type | PID Control | Control cycle: relay output 20 sec / SSR drive output 2 sec | | | | | |
| Relay | Mechanical | ≥ 10,000,000 operations (18,000 operations/time) | | | | | |
| life cycle | Electrical | ≥ 100,000 operations (900 operations/time) | | | | | |
| Dielectric | strength | Between input terminal and power terminal: 2,000 VAC \sim 50/60 Hz for 1 min | | | | | |
| Vibration | 1 | 0.75 mm amplitude at frequency of 5 to 55 Hz (for 1 min) in each X, Y, Z direction for 2 hours | | | | | |
| Insulatio | n resistance | ≥ 100 MΩ (500 VDC== megger) | | | | | |
| Noise im | munity | Square shaped noise (pulse width: 1 μ s) by noise simulator ± 2 kV R-phase, S-phase | | | | | |
| Memory retention | | \approx 10 years (non-volatile semiconductor memory type) | | | | | |
| Ambient | temperature | -10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation) | | | | | |
| Ambient humidity | | 35 to 85%RH, storage: 35 to 85%RH (no freezing or condensation) | | | | | |
| Insulation type | | Double or reinforced insulation (mark: , dielectric strength between the measuring input part and the power part: 2 kV) | | | | | |
| Approval | | CE . 91 | | | | | |
| Unit weight (packaged) | | • TAS: $\approx 69 \text{ g} (\approx 107 \text{ g})$ • TAL: $\approx 147 \text{ g} (\approx 232 \text{ g})$ • TAM: $\approx 109 \text{ g} (\approx 171 \text{ g})$ | | | | | |

Unit Descriptions



1. Input type of sensor

Temperature can be set within the input range of sensor. Refer to 'Input Type and Using Range'.

2. Temperature unit display 3. Temperature range display

4. SV (setting value) dial

When changing SV, it is applied after 2 sec for the stable input.

5. Control output Indicator (OUT)

Turns ON when control output is ON (relay /SSR drive).

6. Deviation indicator

| Displays deviation of PV (present value) based on SV. | | | | | | | | | |
|---|---------|-----------|---------|--|--|--|--|--|--|
| Condition | ▲ (Red) | • (Green) | ▼ (Red) | | | | | | |
| Over 10 °C | ON | - | - | | | | | | |
| 2 to 10 °C | ON | ON | - | | | | | | |
| Under ±2 °C (control output stop) | - | ON | - | | | | | | |
| -2 to -10 °C | - | ON | ON | | | | | | |
| Over -10 °C | - | - | ON | | | | | | |

7. Control type selection switch Select PID control (front part) or

ON/OFF control (rear part) using switch.

| TAS | Right side relative to front | PID ON/OFF |
|------------|---------------------------------------|------------|
| TAM TAL | Left side relative to the front | ON/OFF PID |

Initial Display When Power is ON

When power is supplied, all indicators are turned ON for 2 sec. After turn OFF, it returns to RUN mode.

Errors

| Indicator | Description | Troubleshooting | | |
|--|---|--------------------------------------|--|--|
| $\blacktriangle + \spadesuit + \blacktriangledown$ | Flashes when input sensor is disconnected or sensor is not connected. | Check input sensor status. | | |
| | Flashes when PV is higher than input range. | When input is within the rated input | | |
| ▼ | Flashes when PV is lower than input range. | range, this display disappears. | | |

Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.



| Covies | Body | | | Panel cut-out | | | | | | |
|--------|------------|------|------|---------------|----|------|------------|------------|--------------------|--------------------|
| Series | A | В | С | D | E | F | G | Н | I | J |
| TAS | 4 8 | 14 | 66.7 | 5.2 | 52 | 44.8 | ≥ 65 | ≥ 65 | 45 ^{+0.5} | 45+0.5 |
| ТАМ | □72 | 14.7 | 64.5 | 6.5 | - | - | ≥ 90 | \geq 90 | 68+0.7 | 68 0 0 |
| TAL | □96 | 14.7 | 64.5 | 6.5 | - | - | ≥ 115 | ≥ 115 | 92 ^{+0.8} | 92 ^{+0.8} |

Bracket





Installation Method

TAS Series





Insert the unit into a panel, fasten the bracket by pushing with a flathead screwdriver.

Connections



Crimp Terminal Specifications

• Unit: mm, Use the crimp terminal of follow shape.

Ø ≤5.8 ≥3.0

≤5.8^{≥3,0}

Fork crimp terminal

Round crimp terminal